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# ABSOLUTE RELIABILITY AND CONCURRENT VALIDITY OF THE STRYD SYSTEM FOR THE ASSESSMENT OF RUNNING STRIDE KINEMATICS AT DIFFERENT VELOCITIES

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## ABSTRACT

García-Pinillos, F, Roche-Seruendo, LE, Marcen-Cinca, N, Marco-Contreras, LA, and Latorre-Román, PA. Absolute reliability and concurrent validity of the Stryd system for the assessment of running stride kinematics at different velocities. *J Strength Cond Res XX(X): 000–000, 2018*—This study aimed to determine the absolute reliability and to evaluate the concurrent validity of the Stryd system for measuring spatiotemporal variables during running at different velocities (8–20 km·h<sup>-1</sup>) by comparing data with another widely used device (the OptoGait system). Eighteen trained male endurance runners performed an incremental running test (8–20 km·h<sup>-1</sup> with 3-minute stages) on a treadmill. Spatiotemporal parameters (contact time [CT], flight time [FT], step length [SL], and step frequency [SF]) were measured using 2 different devices (Stryd and OptoGait systems). The Stryd system showed a coefficient of variation (CV) <3%, except for FT (3.7–11.6%). The OptoGait achieved CV <4%, except for FT (6.0–30.6%). Pearson correlation analysis showed large correlations for CT and FT, and almost perfect for SL and SF over the entire protocol. The intraclass correlation coefficients partially support those results. Paired *t*-tests showed that CT was underestimated ( $p < 0.05$ , effect size [ES] > 0.7; ~4–8%), FT overestimated ( $p < 0.05$ , ES > 0.7; ~7–65%), whereas SL and SF were very similar between systems (ES < 0.1, with differences <1%). The Stryd is a practical portable device that is reliable for measuring CT, FT, SL, and SF during running. It provides accurate SL and SF measures but underestimates CT (0.5–8%) and overestimates FT (3–67%) compared with a photocell-based system.

<sup>AU3</sup> **KEY WORDS** biomechanics, technology

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## INTRODUCTION

Interest in running gait analysis is appropriate in both an injury prevention (11,17) and an athletic performance context (1,3,13,18). Although previous methods of analysis have generally required well-equipped research laboratories, recently, there has been a move to produce low-cost, portable gait analysis equipment. This has allowed researchers to remove participants from an artificial laboratory environment and measure participants in a more natural environment (14).

In the current study, the authors compared Stryd data with a widely used device for assessing spatiotemporal variables during locomotion. The OptoGait system is composed of photoelectric cells positioned along transmitting-receiving bars of 1 m in length with a maximum distance of 6 m between bars. The transmitting-receiving bars contain infrared light-emitting diodes (LEDs), enabling communication between the 2 bars. When a subject passes between the transmitting bar and the receiving bar, the system automatically calculates spatiotemporal parameters by sensing interruptions in communication. The assessment results of this gait analysis system have been previously validated in healthy adults walking at a comfortable speed (9), and the system has been used to examine spatiotemporal parameters of athletes when running at different velocities and under different conditions (12,16).

Stryd system (www.stryd.com) is a pioneer in manufacturing wearable power meters for running. Power meters have helped performance-focused cyclists revolutionize their training and racing (15), and the same may soon be accomplished for runners. This power meter for runners is a foot pod that attaches to a running shoe to measure 12 metrics to quantify performance: pace, distance, elevation, running power, form power, cadence, ground contact time (CT), vertical oscillation, and leg stiffness. This is a relatively new tool, and yet, there are no data to demonstrate validity and reliability of this device, making this type of study beneficial. <sup>AU4</sup>

**TABLE 1.** Coefficient of variation (%) of the spatiotemporal parameters (CT, FT, SL, and SF) at different running velocities (8–20 km·h<sup>-1</sup>) from OptoGait system and from Stryd system.

Speed (km·h <sup>-1</sup> )	Contact time (CT)		Flight time (FT)		Step length (SL)		Step frequency (SF)	
	Stryd	OptoGait	Stryd	OptoGait	Stryd	OptoGait	Stryd	OptoGait
8	1.46	3.01	11.60	30.58	1.32	3.78	1.31	3.13
9	1.38	2.91	9.38	24.17	1.38	3.61	1.33	3.30
10	1.53	2.90	7.35	18.62	1.22	3.39	1.19	3.14
11	1.43	2.79	5.78	14.01	1.13	3.28	1.11	3.06
12	1.37	2.59	5.21	11.44	1.24	3.04	1.19	2.77
13	1.22	2.56	4.27	9.05	1.09	2.74	1.05	2.79
14	1.27	2.48	4.18	8.26	1.14	2.63	1.13	2.52
15	1.34	2.41	4.29	7.05	1.33	2.24	1.26	2.35
16	1.91	2.53	4.59	6.46	1.20	1.98	1.17	2.33
17	1.56	2.38	3.73	6.38	1.32	2.02	1.29	2.30
18	1.98	2.33	5.11	6.37	1.86	2.08	1.69	2.15
19	2.23	2.45	5.39	6.41	2.02	2.24	1.87	2.27
20	2.32	2.48	7.56	6.01	2.08	2.66	2.01	3.54

The variety of available technologies for gait analysis (e.g., accelerometers, gyroscopes, force plates, pressure plates, and photoelectric cells) implies that a variety of devices should exist for analyzing stride characteristics. However, some of these devices have not yet been validated. The validity and reliability of a gait analysis system are essential to determine whether results are due to changes in gait pattern or are simply systematic

measurement errors. Therefore, the aim of the current study is to determine the absolute reliability (within-subject variation) and to evaluate the concurrent validity of the Stryd system for measuring spatiotemporal variables during running at different velocities (usual for endurance runners at training and competing, 8–20 km·h<sup>-1</sup>) by comparing data with a widely used device for this purpose (i.e., the OptoGait system).

**TABLE 2.** SEM of the spatiotemporal parameters (CT, FT, SL, and SF) at different running velocities (8–20 km·h<sup>-1</sup>) from OptoGait system and from Stryd system.

Speed (km·h <sup>-1</sup> )	Contact time (CT)		Flight time (FT)		Step length (SL)		Step frequency (SF)	
	Stryd	OptoGait	Stryd	OptoGait	Stryd	OptoGait	Stryd	OptoGait
8	0.005	0.005	0.008	0.009	1.345	1.259	2.483	2.269
9	0.004	0.005	0.007	0.009	1.228	1.179	2.138	2.068
10	0.003	0.004	0.005	0.007	1.071	1.032	1.746	1.777
11	0.003	0.003	0.005	0.007	1.479	1.539	2.213	2.234
12	0.003	0.003	0.005	0.007	1.572	1.539	2.227	2.229
13	0.003	0.002	0.004	0.005	1.583	1.497	2.108	2.103
14	0.003	0.002	0.004	0.005	1.704	1.757	2.198	2.179
15	0.002	0.002	0.003	0.004	1.794	1.730	2.207	2.164
16	0.002	0.002	0.003	0.004	1.930	1.881	2.318	2.355
17	0.002	0.002	0.003	0.004	2.146	2.151	2.507	2.529
18	0.001	0.002	0.004	0.004	2.412	2.484	2.771	2.787
19	0.001	0.002	0.003	0.003	2.252	2.278	2.535	2.591
20	0.001	0.003	0.003	0.003	2.013	2.079	2.211	2.406

**TABLE 3.** Pearson correlation between kinematics variables from Stryd vs. Optogait over an incremental running test (8–20 km·h<sup>-1</sup>).

Speed (km·h <sup>-1</sup> )	8	9	10	11	12	13	14	15	16	17	18	19	20
Contact time	0.657*	0.636*	0.574†	0.525†	0.433	0.435	0.507†	0.504†	0.503†	0.453	0.415	0.429	0.078
Flight time	0.602*	0.656*	0.685*	0.703*	0.722*	0.739†	0.722†	0.782†	0.811†	0.800†	0.775†	0.680†	0.834†
Step length	0.934†	0.999†	0.999†	0.999†	0.999†	0.998†	0.997†	0.998†	0.999†	0.999†	0.999†	0.997†	0.991†
Step frequency	0.959†	0.996†	0.999†	0.999†	0.999†	0.999†	0.999†	0.999†	0.999†	0.999†	0.999†	0.999†	0.999†

\**p* < 0.01.  
 †*p* < 0.05.  
 ‡*p* < 0.001.

AU12

**METHODS**

**Experimental Approach to the Problem**

With the introduction of new wireless devices, establishment of their reliability and validity are essential before practical use. In this study, the Stryd system was compared with the OptoGait system for measuring spatiotemporal variables during running at different velocities (8–20 km·h<sup>-1</sup>).

**AU5 Subjects**

**AU6** A group of 18 recreationally trained male endurance runners (age range: 19–46 years; age: 34 ± 7 years; height: 1.76 ± 0.05 m; body mass: 70.5 ± 6.2 kg) voluntarily participated in this study. All participants met the inclusion criteria: (a) older than 18 years, (b) able to run 10 km in less than 40 minutes, (c) training on a treadmill at least once per week, and (d) not suffering from any injury (points 3 and 4 related to the last 6 months before the data collection). After receiving detailed information on the objectives and procedures of the study, each subject signed an informed consent form to participate, which complied with the ethical standards of the World Medical Association’s Declaration of Helsinki (2013). It was made clear that the participants were free to leave the study if they saw fit. The study was approved by the Ethics **AU8** Committee of the San Jorge University (Zaragoza, Spain).

**Procedures**

The study was conducted in June 2017. At the time of these observations, the subjects had completed between 6 and 7 months of training. Subjects were individually tested on one day (between 16:00 and 21:00 hours). Before all testing, subjects refrained from severe physical activity for at least 48 hours and all testing was at least 3 hours after eating. Tests were performed with the subjects’ usual training shoes to measure their typical performance.

Subjects performed an incremental running test on a motorized treadmill (HP cosmos Pulsar 4P; HP cosmos Sports & Medical, GmbH, Nußdorf, Germany). The initial speed was set at 8 km·h<sup>-1</sup> and speed increased by 1 km·h<sup>-1</sup> every 3 minutes until running speed reached 20 km·h<sup>-1</sup>. The slope was maintained at 1% (0.9°). The treadmill protocol was preceded by a standardized 10-minute accommodation programme (5 minutes walking at 5 km·h<sup>-1</sup>, and 5 minutes running at 10 km·h<sup>-1</sup>). Athletes were experienced in running on a treadmill.

*Materials and Testing.* (a) Anthropometry: For descriptive purposes, height (cm) and body mass (kg) were measured.

(b) Biomechanics: Spatiotemporal parameters were measured using 2 different devices:

**TABLE 4.** Intraclass correlation coefficients between kinematics variables from Stryd vs. Optogait over an incremental running test (8–20 km·h<sup>-1</sup>).

Speed (km·h <sup>-1</sup> )	8	9	10	11	12	13	14	15	16	17	18	19	20
Contact time	0.457	0.463	0.416	0.386	0.303	0.330	0.407	0.400	0.380	0.329	0.294	0.381	0.063
Flight time	0.555	0.599	0.655	0.679	0.702	0.726	0.758	0.768	0.799	0.778	0.744	0.635	0.806
Step length	0.934	0.998	0.999	0.999	0.999	0.998	0.997	0.998	0.999	0.999	0.999	0.997	0.991
Step frequency	0.956	0.995	0.999	0.999	0.999	0.999	0.999	0.999	0.999	0.999	0.999	0.997	0.983

- The OptoGait system (Optogait; Microgate, Bolzano, Italy) was previously validated for the assessment of spatiotemporal parameters of the gait of young adults (9). As indicated by Lee et al. (9), the OptoGait achieved a high level of correlation with all spatiotemporal parameters by intraclass correlation coefficients (ICCs) (0.785–0.952), coefficients of variation (1.66–4.06%), SEM (2.17–5.96%), and minimum detectable change (6.01–16.52%). The system detects any interruptions and therefore measures both CT and flight time (FT) with a precision of 1/1,000 seconds. The 2 parallel bars of the device system were placed on the side edges of the treadmill at the same level as the contact surface. Contact time, FT, step length (SL), and step frequency (SF or cadence) were measured for every step during the treadmill test and were defined as follows:
  - CT (second): time from when the foot contacts the ground to when the toes lift off the ground.
  - FT (second): time from toe-off to initial ground contact of consecutive footfalls (e.g., right-left).
  - SL (meter): length the treadmill belt moves from toe-off to initial ground contact in successive steps.
  - SF or cadence (steps per minutes): number of ground contact events per minute.
- Stryd (Stryd Powermeter; Stryd, Inc., Boulder, CO, USA): a relatively new device, which estimates power in watts. Stryd is carbon fiber–reinforced foot pod (attached to your shoe) that weights 9.1 g. Based on a 6-axis inertial motion sensor (3-axis gyroscope and 3-axis accelerometer), this device provides spatiotemporal data including CT and SF. From CT and SF, in addition

to running velocity, the authors calculated FT and SL as follows:

$$FT (s) = \text{step time (s)} - CT (s), \quad (1)$$

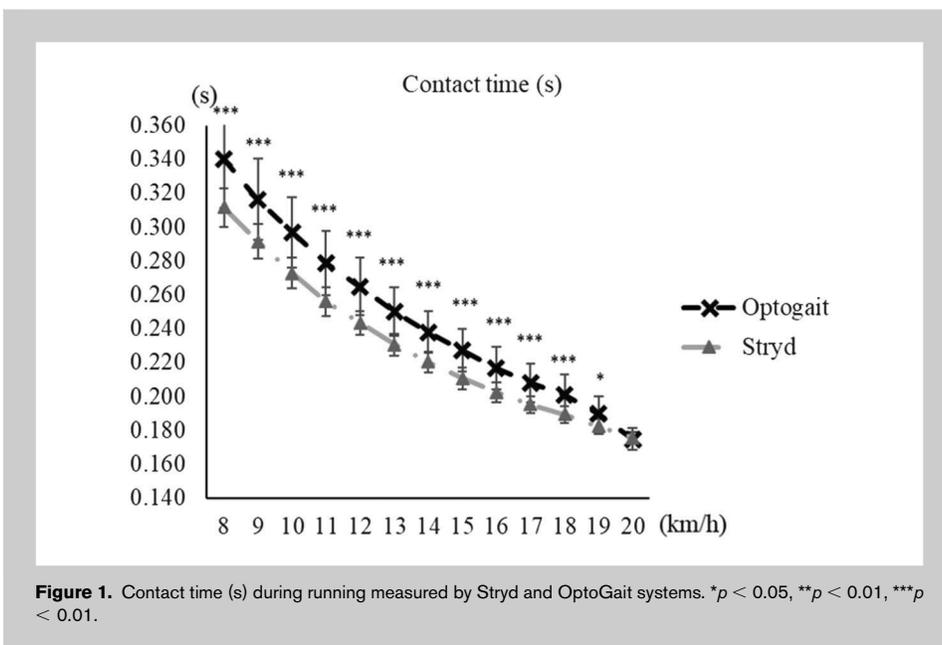
where step time is the time from the beginning of the step cycle (take-off) to the end (previous frame to take-off).

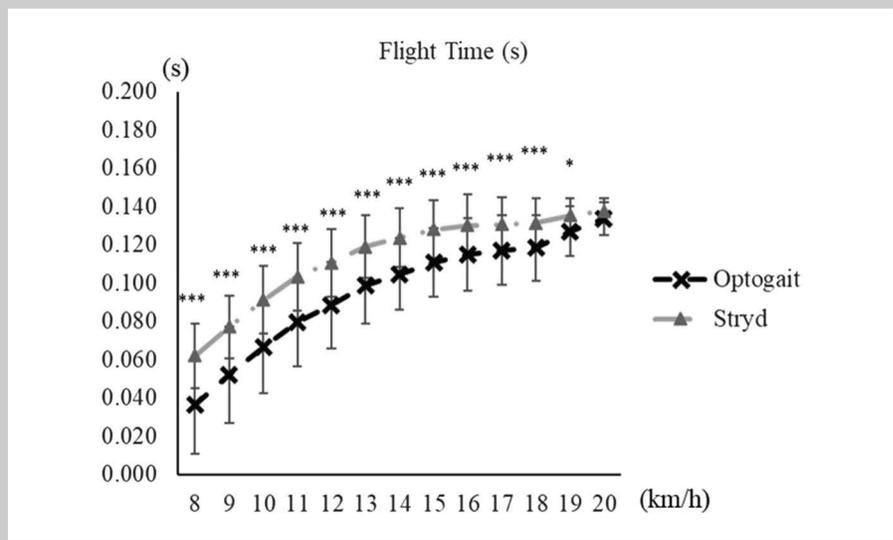
$$\text{step time (s)} = 60/SF \text{ (steps/min)}.$$

$$SL (m) = \text{running velocity (m} \cdot \text{min}^{-1}) / SF(\text{steps/min}). \quad (2)$$

### Statistical Analyses

Descriptive statistics are represented as mean (*SD*). Tests of normal distribution and homogeneity (Shapiro-Wilk and Levene’s test, respectively) were conducted on all data before analysis. Coefficient of variation (CV, %) and *SEM* were calculated as a measure of absolute reliability (within-subject variation and *SD* of a sampling distribution, respectively) (26). Intraclass correlation coefficients were calculated between OptoGait and Stryd data for each spatiotemporal variable analyzed (CT, FT, SL, and SF). Values less than 0.5 are indicative of poor reliability, values between 0.5 and 0.75 indicate moderate reliability, values between 0.75 and 0.9 indicate good reliability, and values greater than 0.90 indicate excellent reliability (8). To determine concurrent validity, a Pearson correlation analysis was also performed between OptoGait and Stryd data. The following criteria were adopted to interpret the magnitude of correlations between measurement variables: <0.1 (trivial), 0.1–0.3 (small), 0.3–0.5 (moderate), 0.5–0.7 (large), 0.7–0.9 (very large), and 0.9–1.0 (almost perfect) (7). Pairwise comparisons of mean (*t*-test) were also conducted between data (CT, FT, SL, and SF) from the 2 devices (OptoGait and Stryd) at different running speeds (8–20 km·h<sup>-1</sup>). In addition, the magnitude of the differences between values was also interpreted using the Cohen’s *d* effect size (ES) (19). Effect sizes of less than 0.4 represented a small magnitude of change, whereas 0.41–0.7 and greater than 0.7 represented moderate and large magnitudes of change, respectively (19). The level of significance used was *p* < 0.05. Data analysis was





**Figure 2.** Flight time (s) during running measured by Stryd and OptoGait systems. \* $p < 0.05$ , \*\* $p < 0.01$ , \*\*\* $p < 0.001$ .

performed using SPSS (version 21; SPSS, Inc., Chicago, IL, USA).

**RESULTS**

**Reliability**

**T1** Table 1 shows the CV (as a measure of absolute reliability) of spatiotemporal parameters at different running velocities from both Stryd and OptoGait. For the Stryd system, CV ranged between 1.2–2.3% (CT), 3.7–11.6% (FT), 1.1–2.1% (SL), and 1.1–2.0% (SF), whereas for the OptoGait system,

CV was 2.3–3.0% (CT), 6.0–30.6% (FT), 2.0–3.8% (SL), and 2.2–3.6% (SF). In addition, the SEM is provided in Table 2. **T2**

**Validity**

The Pearson correlation analysis is shown in Table 3 (CT, FT, SL, and SF or cadence at 8–20 km·h<sup>-1</sup> running velocities). Contact time from both devices showed large correlations (0.5–0.7,  $p < 0.05$ ) at low speeds (8–11 km·h<sup>-1</sup>) and race speeds (14–16 km·h<sup>-1</sup>). Flight time from OptoGait and Stryd showed large and very large correlations, respectively (0.602 <  $r$  > 0.834,  $p < 0.05$ ), over the velocities tested (8–20 km·h<sup>-1</sup>). Step **T3**

length and SF from both devices were nearly perfectly correlated ( $r > 0.9$ ,  $p < 0.001$ ) at every running velocity tested.

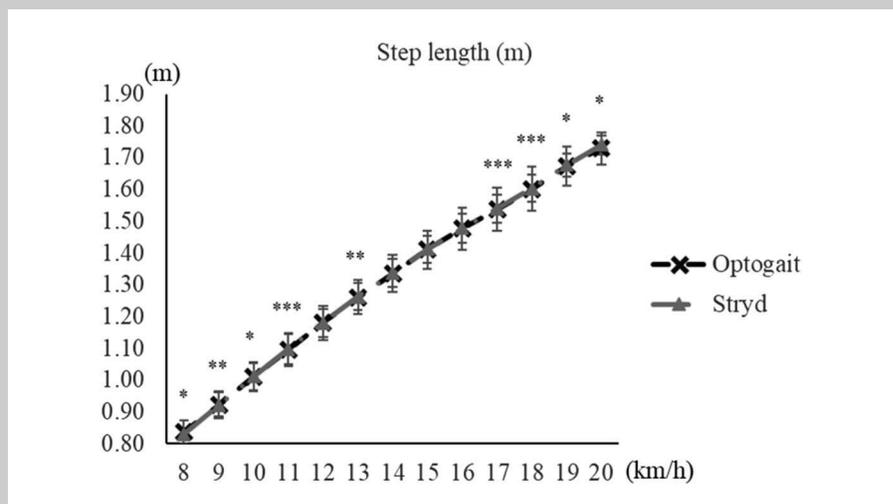
The ICCs between kinematic variables from both Stryd vs. OptoGait systems over the entire protocol (8–20 km·h<sup>-1</sup>) are included in Table 4. Contact time showed a low coefficient (<0.5), FT a moderate coefficient (0.5–0.75), whereas SL and SF showed excellent coefficients (>0.9). **T4**

A paired  $t$ -test demonstrated some significant differences ( $p < 0.05$ ) and large ES (>0.7) in the variables analyzed (CT, FT, SL, and cadence) (Figures 1–4, respectively). Contact **F1**

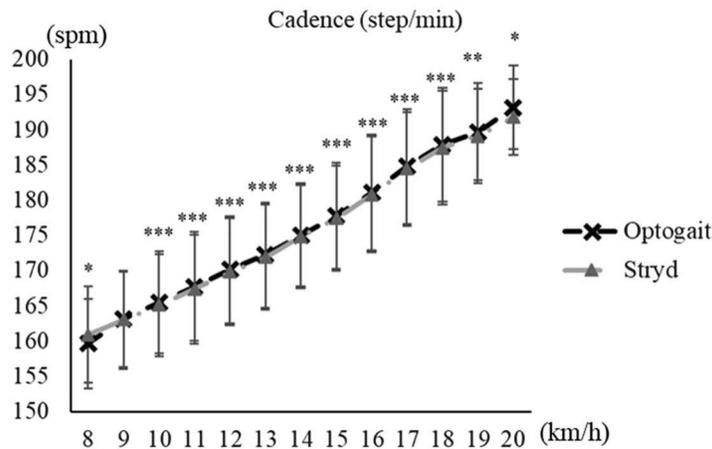
time (Figure 1) was underestimated for Stryd compared with OptoGait data (8–18 km·h<sup>-1</sup>,  $p < 0.001$ , and ES > 0.7; ~6–8%). Differences were smaller at 19 km·h<sup>-1</sup> ( $p < 0.05$  and ES > 0.7; ~4%), and no differences were observed at 20 km·h<sup>-1</sup> ( $p \geq 0.05$  and ES < 0.1; ~0.5%). **F2**

Flight time (Figure 2) was overestimated for Stryd based on OptoGait data at running velocities between 8 and 19 km·h<sup>-1</sup> ( $p < 0.05$ , ES > 0.7; from ~65% at 8 km·h<sup>-1</sup> to ~7% at 19 km·h<sup>-1</sup>). No significant differences were found at 20 km·h<sup>-1</sup> ( $p \geq 0.05$  and ES = 0.57; ~3%). **F3**

Step length from both devices is shown in Figure 3. **F3**



**Figure 3.** Step length (cm) during Running measured by Stryd and OptoGait systems. \* $p < 0.05$ , \*\* $p < 0.01$ , \*\*\* $p < 0.001$ .



**Figure 4.** Step frequency (cadence, step per minute) during running measured by Stryd and OptoGait systems. \* $p < 0.05$ , \*\* $p < 0.01$ , \*\*\* $p < 0.001$ .

F4

$p$  values show significant differences ( $p < 0.05$ ) between data from Stryd and OptoGait at most analyzed velocities, although Cohen's  $d$  showed a very small magnitude of changes ( $ES < 0.1$ ), with Stryd data overestimated compared with OptoGait data ( $<1\%$ ). Likewise, significant differences ( $p < 0.05$ ) were found in cadence between the 2 devices (Figure 4), but Cohen's  $d$  reported a very small change ( $ES < 0.1$ ) with differences smaller than 1%.

## DISCUSSION

This study aimed to determine the absolute reliability and to evaluate the concurrent validity of the Stryd system for measuring spatiotemporal variables during running at different velocities (8–20  $\text{km}\cdot\text{h}^{-1}$ ) by comparing data with a device widely used for this purpose (OptoGait system). The major findings of this study were (a) CV, as a measure of reliability, was lower in all analyzed variables for the Stryd system than for the OptoGait system ( $<5\%$  in all cases, except for FT), whereas SEM was almost identical for every variable over the entire protocol (8–20  $\text{km}\cdot\text{h}^{-1}$ ), and (b) concurrent validity of the Stryd and OptoGait systems regarding spatiotemporal variables is not yet settled: moderate for CT, low for FT, and very high for SL and SF. Results from Pearson correlation analysis indicated a strong concurrent validity over the entire range of running velocities (8–20  $\text{km}\cdot\text{h}^{-1}$ ), with large correlations in CT, very large correlations in FT, and almost perfect correlations in SL and SF. The ICCs partially provide support to those results with excellent coefficients for SL and SF and moderate for FT, but poor coefficients for CT (over the entire protocol). In addition, the paired  $t$ -test let us improve our comparison and some interesting findings are worth noting: (a) The Stryd system underestimated CT (up to  $\sim 8\%$  at low velocities)

and overestimated FT (up to  $\sim 65\%$  at low velocities) compared with the OptoGait system, with reduced differences at high running velocities, and (b) despite differences in  $p$  values, the very small magnitude of changes reported suggests that SL and SF (from the Stryd system) are valid variables over running velocities of 8–20  $\text{km}\cdot\text{h}^{-1}$ , compared with the OptoGait system.

As mentioned earlier, scientists have discovered the potential of accelerometers (and inertial measurement units [IMUs]) in assessing gait analysis without the restrictions of laboratory technology. Having the chance to measure athletes or clients in a natural

environment and using less expensive and more time-efficient equipment is a huge step forward for coaches and clinicians. Nevertheless, this advantage would be worthless if the data were not valid. The Stryd system (based on a 6-axis inertial motion sensor: 3-axis gyroscope and 3-axis accelerometer) is mainly a running power meter, but it also provides spatiotemporal variables that are used by coaches and clinicians (information easily accessible to users) as a feedback, necessitating confirmation of the validity of these data.

Comparing between devices and technologies (i.e., photoelectric cells vs. IMUs), the authors hypothesize that differences in temporal variables might be at least partially explained by the height of the OptoGait system's LEDs. As described by Lienhard et al. (10), the LEDs of the OptoGait system are positioned 3 mm above ground, and thereby, sensing of heel contact occurs earlier, whereas sensing of toe lift-off occurs later in the gait cycle (timing differences). In a similar previously published study (4), the authors assessed the reliability and validity of an accelerometer-based system (Myotest) against a photocell-based system (OptoJump) for measuring running stride kinematics. In line with our data, the authors reported CT 34% shorter and FT 64% longer than the photocell-based system. That work (4) also found a good validity in SF. Therefore, the data obtained in the current study agree with those reported by previous studies that compared accelerometer-based systems to photocell-based systems, and our results support the explanation for this discrepancy given by Lienhard et al. (10).

Some final limitations need to be taken into consideration. First, the use of photocell-based systems as the gold standard reference for establishing concurrent validity should be evaluated, instead of instruments that measure ground

reaction force, such as a force platform. Because we do not possess such equipment in our laboratory, the use of the OptoGait system was considered to be an adequate proxy system, given its demonstrated good validity compared with GAITRite system—pressure platform (9) or compared with force platform during jumping tests (5). Furthermore, the OptoGait system is more practical and portable for recording several consecutive steps than force or pressure platforms imbedded into the ground in series where participants often have to adjust SL and target platforms to obtain clearly defined foot contact data. A second consideration is that validation data were obtained from an analysis based on within-subject variation (CV) rather than on different days. Although the number of steps analyzed in 3-minutes of running at these velocities is high (400–500 steps in 3 minutes), our current reliability statistics might not generalize to runs performed several days apart.

**AU9** To sum up, based on traditional thresholds, the absolute (i.e., CV) reliability of CT, FT, SL, and SF derived using the Stryd device were classified as adequate for running assessments, and this suggests that the Stryd is useful for monitoring individuals and quantifying changes in functional performance over time. However, the concurrent validity of Stryd as compared to OptoGait was low-moderate for CT and FT, and excellent for SL and SF. The paired comparisons added to those correlations showed that the Stryd system underestimated CT (0.5–8%) and overestimated FT (3–67%) compared with OptoGait system, with reduced differences at elevated running velocities (8–20 km·h<sup>-1</sup>). However, SL and SF were valid variables (<1%) over the entire range of running velocities, as compared with the OptoGait system.

### PRACTICAL APPLICATIONS

From a practical point of view and considering that both systems are widely used, scientists and clinicians should know that both devices showed an adequate reliability for running assessments, and thereby, spatiotemporal parameters reported from these devices can be compared over time (if using the same device). However, the clients also should be aware about the limitations of comparing data reported from these 2 devices.

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